

INTRODUCTION

- ▶ We consider a full-duplex MIMO decode-and-forward relay with:
 - ▶ **limited dynamic range** at receive and transmit side.
 - ▶ **self-interference** due to simultaneous reception and transmission.
- ▶ We propose a cancellation-suppression design that aims to:
 - ▶ maximize the **signal-to-interference-plus-noise** ratio at the relay.
 - ▶ control the **distortion** in the relay-destination link.

SYSTEM MODEL

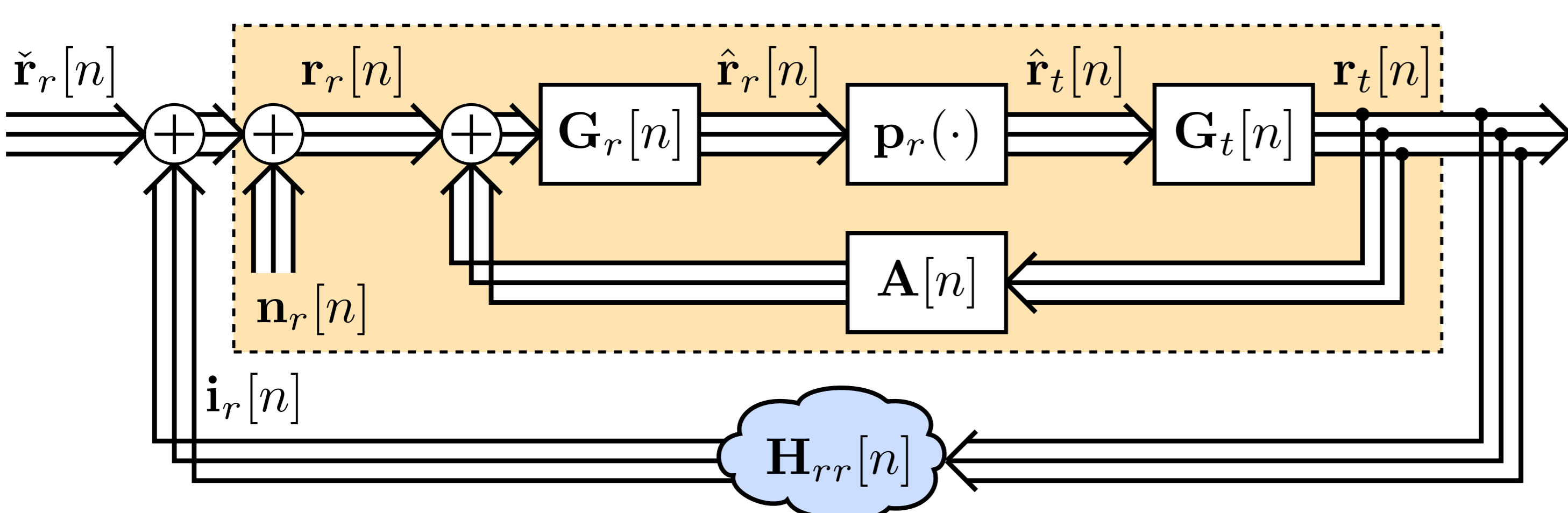


Figure: System model of a relay incorporating the cancellation-suppression architecture.

- ▶ The link consists of a source node (\mathcal{S}), a relay node (\mathcal{R}), and a destination node (\mathcal{D}) with the following characteristics:
 - ▶ \mathcal{S} has M_t transmit antennas and transmits $\mathbf{s}_t[n]$.
 - ▶ \mathcal{D} has M_r receive antennas and receives $\mathbf{d}_r[n]$.
 - ▶ \mathcal{R} has N_r receive antennas and N_t transmit antennas, and transmits $\mathbf{r}_t[n]$ while receiving $\mathbf{r}_r[n]$.
- ▶ The received signal at \mathcal{R} consists of the the information signal $\check{\mathbf{r}}_r[n] = \mathbf{H}_{sr}[n] * \mathbf{s}_t[n]$, the self-interference $\mathbf{i}_r[n] = \mathbf{H}_{rr}[n] * \mathbf{r}_t[n]$ and the noise $\mathbf{n}_r[n]$:

$$\mathbf{n}_r[n] = \mathbf{n}_i[n] + \mathbf{v}_r[n] + \mathbf{H}_{rr}[n] * \mathbf{v}_t[n] \quad (1)$$

where $\mathbf{n}_i[n] \sim \mathcal{CN}(\mathbf{0}, \sigma^2 \mathbf{I})$ is the receiver input noise, $\mathbf{v}_t[n] \sim \mathcal{CN}(\mathbf{0}, \delta \text{diag} \mathbb{E}\{\mathbf{r}_t[n] \mathbf{r}_t^H[n]\})$ models transmitter imperfections, and $\mathbf{v}_r[n] \sim \mathcal{CN}(\mathbf{0}, \gamma \text{diag} \mathbb{E}\{\mathbf{r}_c[n] \mathbf{r}_c^H[n]\})$, with $\mathbf{r}_c[n] = \mathbf{r}_r[n] - \mathbf{v}_r[n]$, models receiver dynamic range.

PROBLEM SETTING AND DESIGN

- ▶ The cancellation-suppression architecture consists of the L_a -th order cancellation filter $\mathbf{A}[n]$, the L_r -th order filter $\mathbf{G}_r[n]$ and the L_t -th order filter $\mathbf{G}_t[n]$.
- ▶ The signal-to-interference-plus-noise ratio after processing is defined as

$$\text{SINR}_{\mathcal{R}} = \frac{\mathbb{E}\{\|\mathbf{G}_r[n] * \check{\mathbf{r}}_r[n]\|^2\}}{\mathbb{E}\{\|\mathbf{G}_r[n] * \mathbf{n}_r[n] + \mathbf{G}_r[n] * (\mathbf{A}[n] + \mathbf{H}_{rr}[n]) * \mathbf{G}_t[n] * \hat{\mathbf{r}}_t[n]\|^2\}}$$

- ▶ Filters $\mathbf{A}[n]$, $\mathbf{G}_r[n]$ and $\mathbf{G}_t[n]$ are designed as the solution to the problem:

$$\begin{aligned} & \text{maximize}_{\mathbf{A}[n], \mathbf{G}_t[n], \mathbf{G}_r[n]} \text{SINR}_{\mathcal{R}} \\ & \text{subject to} \quad \mathbb{E}\{\|\mathbf{r}_t[n]\|^2\} \leq P_{max} \end{aligned} \quad (2)$$

- ▶ The solution for $\mathbf{A}[n]$ is $\mathbf{A}[n] = -\mathbf{H}_{rr}[n]$.
- ▶ We decouple $\mathbf{G}_t[n]$ and $\mathbf{G}_r[n]$ by designing $\mathbf{G}_t[n]$ as the solution to

$$\begin{aligned} & \text{minimize}_{\mathbf{G}_t[n]} \mathbb{E}\{\|\mathbf{i}_r[n]\|^2\} + \mathbb{E}\{\|\mathbf{H}_{rr}[n] * \mathbf{v}_t[n]\|^2\} \\ & \text{subject to} \quad \mathbf{H}_{rd}[n] * \mathbf{G}_t[n] = \mathbf{H}_{rd}^{(eq)}[n] \\ & \quad \mathbb{E}\{\|\mathbf{r}_t[n]\|^2\} \leq P_{max} \end{aligned} \quad (3)$$

- ▶ Linear constraints preclude trivial solutions and control the distortion in the relay-destination link.

DESIGN

- ▶ Problem (3) is equivalent to

$$\begin{aligned} & \text{minimize}_{\mathbf{g}_t} \mathbf{g}_t^H (\mathbf{P}_i + \mathbf{R}_i) \mathbf{g}_t \\ & \text{subject to} \quad \mathbf{H}_{rd} \mathbf{g}_t = \mathbf{h}_{rd}^{(eq)} \\ & \quad \mathbf{g}_t^H \mathbf{R} \mathbf{g}_t \leq P_{max} \end{aligned} \quad (4)$$

- ▶ After some calculations, problem (4) can be expressed as a standard linear least squares with inequality constraints. For a feasible solution we require that $N_t > M_r$ and $L_t > (M_r L_{rd} / (N_t - M_r)) - 1$.
- ▶ Finally, $\mathbf{G}_r[n]$ is designed as the solution to

$$\text{maximize}_{\mathbf{g}_r} \frac{\mathbf{g}_r^H \mathbf{P}_r \mathbf{g}_r}{\mathbf{g}_r^H \mathbf{P}_n \mathbf{g}_r} \quad (5)$$

- ▶ Problem (5) is recognized as a generalized eigenvalue problem.

SIMULATIONS AND RESULTS

- ▶ The simulations have the following parameters:
 - ▶ $m_s = m_r = M_r = M_t = 2$.
 - ▶ 64-QAM OFDM with 8192 subcarriers, a cyclic prefix length of 1/4 and an oversampling factor of 2.
 - ▶ $\mathbf{H}_{sr}[n]$, $\mathbf{H}_{rd}[n]$ and $\mathbf{H}_{rr}[n]$ have orders $L_{sr} = L_{rd} = L_{rr} = 2$ and gains of 0, 0 and 30 dB, respectively. Additionally, $L_a = L_{rr} = L_t = L_r = 2$ and $P_{max} = 20$ dB.

$$\mathbf{H}_{rd}^{(eq)}[n] = \begin{cases} \mathbf{I}, & n = 0 \\ \mathbf{0}, & n \neq 0 \end{cases}$$

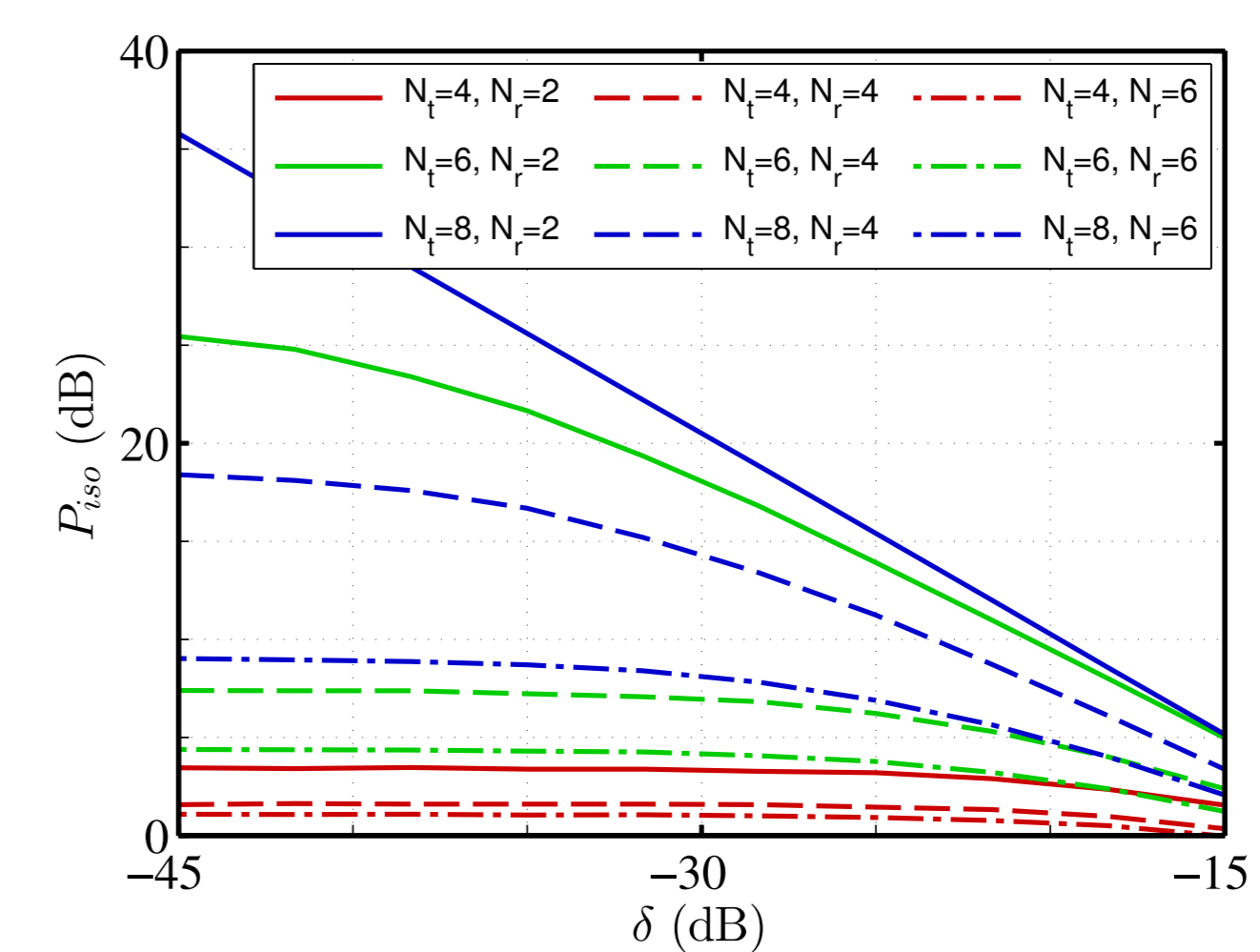


Figure: Self-interference power isolation in terms of the noise level at the transmitter.

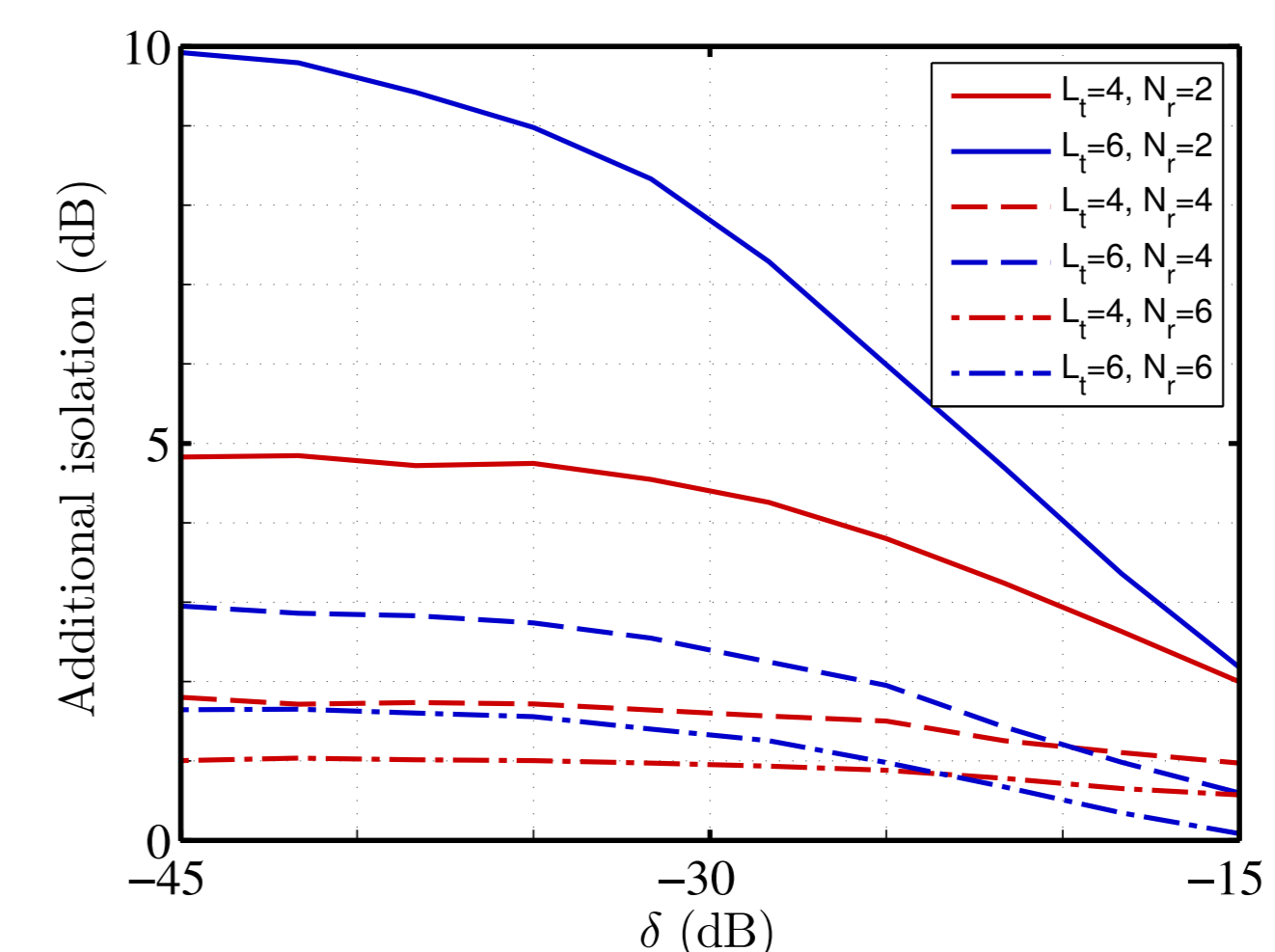


Figure: Additional isolation in terms of the noise level at the transmitter for different orders of $\mathbf{G}_r[n]$.

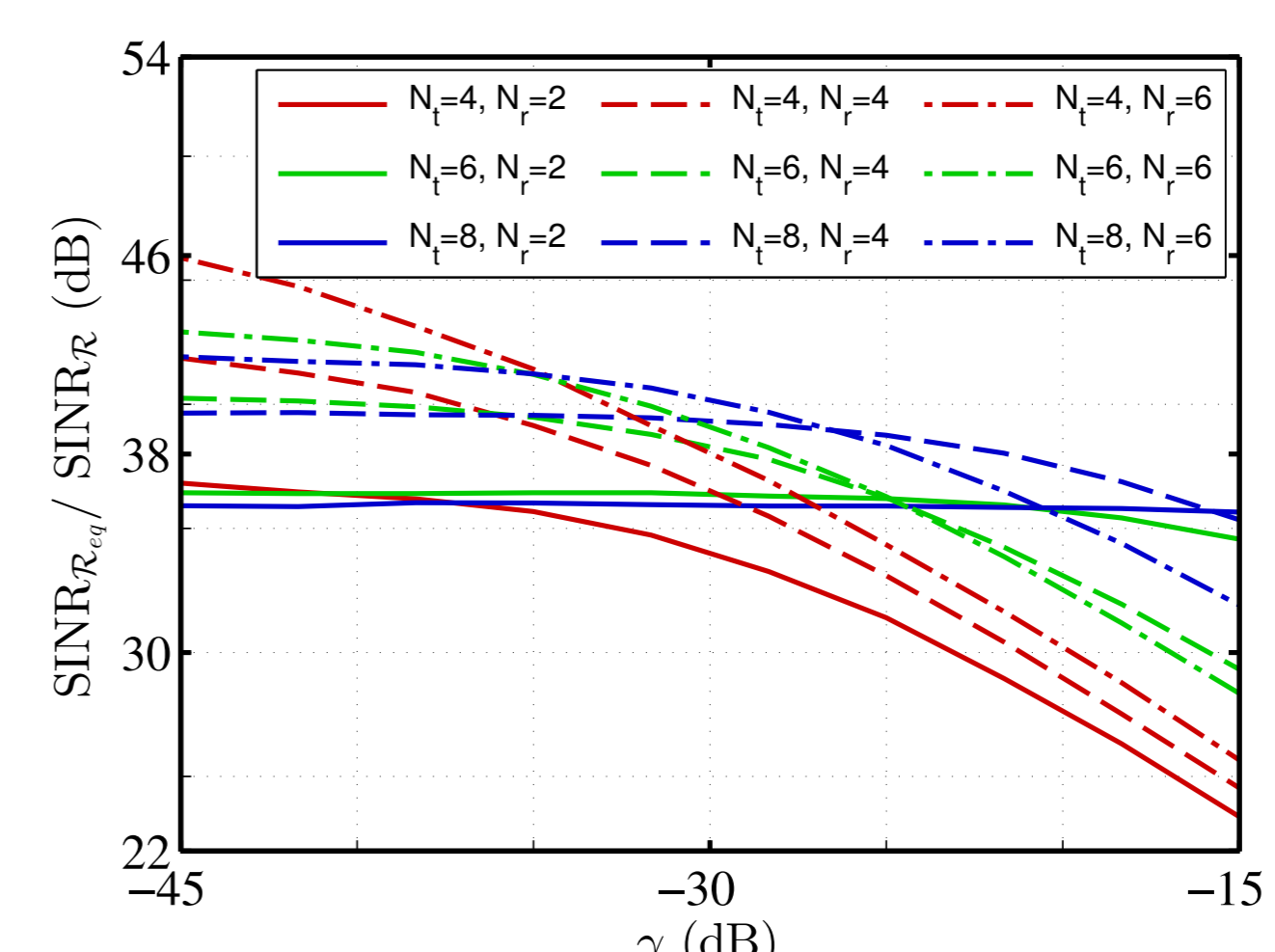


Figure: SINR improvement in terms of the dynamic range of the receiver.